

Theory of Probability

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Sample space

Set Ω is called the *sample space* – a collection of *all possible outcomes* of a random experiment.

Requirement on Ω : a given instance of the experiment must produce a result $\omega \in \Omega$ corresponding to *exactly one* of the elements in Ω .

$\Omega = \{H, T\}$ – a coin tossed once may show either heads or tails.

$\Omega = \{HH, HT, TH, TT\}$ – same coin, but tossed twice. Two tosses of a coin correspond to one experiment

$\Omega = \{1, 2, 3, \dots, 6\}$ – single throw of a dice.

Event

Events are subsets $A \subseteq \Omega$. In our case, all subsets are events.

$$A = \{\text{the number of heads} \leq 1\} = \{HT, TH, TT\} .$$

$$B = \{\text{1st toss} = \text{2nd toss}\} = \{HH, TT\} .$$

$$C = \{\text{the outcome of a die is even}\} = \{2, 4, 6\}.$$

An event A happens if $\omega \in A$.

Ω – a certain event (it always happens).

\emptyset – an impossible event (it never happens).

Event Algebra

$\bigcup_{i=1}^n A_i$ – a union of n events – a set of elements belonging to at least one of the sets A_i .

$\bigcap_{i=1}^n A_i$ – an intersection of n events – a set of elements belonging to all sets A_i .

\bar{A} – complement of A – a set of elements which do not belong to A .

Event Algebra

$$\Omega = \{1, 2, 3, 4, 5, 6\} .$$

$$A = \{\text{dice outcome is even}\} = \{2, 4, 6\} .$$

$$B = \{\text{dice outcome} \geq 3\} = \{3, 4, 5, 6\} .$$

$$A \cup B = \{2, 3, 4, 5, 6\} .$$

$$A \cap B = \{4, 6\} .$$

$$\bar{A} = \{1, 3, 5\} .$$

$$\bar{B} = \{1, 2\} .$$

Events A and B are *mutually exclusive* if $A \cap B = \emptyset$.

Sigma algebra

A sigma-algebra \mathcal{F} is a collection of subsets of Ω , satisfying the following requirements:

1. $\Omega \in \mathcal{F}$
2. $\{A_i\}_{i \in \mathbb{N}} \in \mathcal{F} \implies \bigcup_{i=1}^{\infty} A_n \in \mathcal{F}$
3. $A \in \mathcal{F} \implies \bar{A} \in \mathcal{F}$

Consequently: $\emptyset \in \mathcal{F}$ and $\bigcap_{i=1}^{\infty} A_i \in \mathcal{F}$.

In finite Ω we shall be able to take \mathcal{F} as a powerset of Ω , and \mathcal{F} itself is a set of all events.

Any subset $A \subseteq \mathcal{F}$ is called a *measurable set*.

Probability

A probability (measure) is a function $P : \mathcal{A} \rightarrow \mathbb{R}$ such that:

- ▶ $0 \leq P[A] \leq 1$ for every event $A \in \mathcal{F}$
- ▶ $P[\Omega] = 1$
- ▶ If $\{A_i\}_{i \in \mathbb{N}}$ are mutually exclusive

$$(A_i \cap A_j = \emptyset \text{ for } i \neq j), \text{ then } P\left[\bigcup_{i=1}^{\infty} A_i\right] = \sum_{i=1}^{\infty} P[A_i].$$

The triplet (Ω, \mathcal{F}, P) is called the *probability space*. It is a measure space with the probability function as a measure in this space.

If \mathcal{F} is the powerset of Ω , we omit \mathcal{F} and say that a probability space is a pair (Ω, P) .

Learning and Conditional Probability

Somehow we learn that event B (with $P[B] \neq 0$) happens, i.e. $\omega \in B$.

We may consider *learning* as a process where the probability space (Ω, P) is changing to a new probability space (Ω', P') , where $\Omega' = B$.

We want that there is β , so that $P'[A] = \beta \cdot P[A \cap B]$ for any event A .

As in the new space $P'[B] = P'[\Omega'] = 1$, we have

$$\beta = \frac{1}{P[B \cap B]} = \frac{1}{P[B]}, \text{ i.e.}$$

$$P'[A] = \frac{P[A \cap B]}{P[B]} .$$

The probability $P'[A]$ is denoted by $P[A|B]$ and is called the *conditional probability* of A assuming that B happens.

Learning and Conditional Probability

$\Omega = \{1, 2, 3, 4, 5, 6\}$ for a dice.

$A = \{\text{the outcome is even}\}$.

$B = \{\text{the outcome is 2}\}$.

$$P[B] = \frac{1}{6}.$$

$$P[A] = \frac{3}{6} = \frac{1}{2}.$$

$$P[B|A] = \frac{P[B \cap A]}{P[A]} = \frac{P[B]}{P[A]} = \frac{1}{3}.$$

The probability of outcome 2 given that the outcome was even, is $\frac{1}{3}$.

The Chain rule and the Bayes formula

$$P[A|B] = \frac{P[A \cap B]}{P[B]} \implies P[A \cap B] = P[A|B] \cdot P[B]$$

$$P[B|A] = \frac{P[A \cap B]}{P[A]} \implies P[A \cap B] = P[B|A] \cdot P[A]$$

this is known as the *chain rule*. Hence,

$$P[A \cap B] = P[A|B] \cdot P[B] = P[B|A] \cdot P[A] ,$$

and we obtain the Bayes rule:

$$P[A|B] = \frac{P[B|A] \cdot P[A]}{P[B]} .$$

Random Variables and Probability Distributions

Random variable X is any function $X : \Omega \Rightarrow R$, where R is called the *range* of X .

For any $x \in R$, we define $X^{-1}(x)$ as the event $\{\omega : X(\omega) = x\}$ and use the notation:

$$\mathbb{P}_X[x] = \mathbb{P}[X = x] = \mathbb{P}[X^{-1}(x)] .$$

Note that if $x \neq x'$ then the events $X^{-1}(x)$ and $X^{-1}(x')$ are mutually exclusive.

Random Variables and Probability Distributions

As $\bigcup_{x \in R} X^{-1}(x) = \Omega$, we have:

$$\sum_x P_X[x] = P \left[\bigcup_{x \in R} X^{-1}(x) \right] = P[\Omega] = 1 .$$

If $R = \{x_1, x_2, \dots, x_n\}$, then the sequence of values (p_1, p_2, \dots, p_n) , where $p_i = P_X[x_i]$, is called the *probability distribution* of X .

Independent Events and Random Variables

Events A and B are said to be independent if

$$P[A \cap B] = P[A] \cdot P[B].$$

If $P[A] \neq 0 \neq P[B]$, then independence is equivalent to:

$$P[A|B] = P[A] \quad P[B|A] = P[B] ,$$

so that the probability of A does not change, if we learn that B happened.

Direct Product of Random Variables

The *direct product* of random variables X and Y on a probability space (Ω, \mathbb{P}) is a random variable defined by

$$(XY)(\omega) = (X(\omega), Y(\omega)) .$$

Independent Events and Random Variables

We say that X and Y are independent random variables if for every $x \in R_X$ and $y \in R_Y$:

$$\begin{aligned} \mathbb{P}[X = x, Y = y] &= \mathbb{P}[X^{-1}(x) \cap Y^{-1}(y)] \\ &= \mathbb{P}[X^{-1}(x)] \cdot \mathbb{P}[Y^{-1}(y)] \\ &= \mathbb{P}[X = x] \cdot \mathbb{P}[Y = y] . \end{aligned}$$

This means that the knowledge of the value of Y does not influence the probability distribution of X .

Mean of a Random Variable

By *mean* or *expected value* μ of a random variable X we mean the sum

$$\mu = \sum \omega \cdot X(\omega) .$$

$\omega :$	1	2	3	4	5	6
$X(\omega) :$	0.1	0.2	0.3	0.2	0.1	0.1

$$\mu = E(X) = 0.1 + 0.4 + 0.9 + 0.8 + 0.5 + 0.6 = 3.3 .$$

Dispersion of a Random Variable

Dispersion measures the extent to which the distribution is extended or squeezed. Common examples of statistical dispersion are:

The *variance* $Var(X)$ is the sum:

$$Var(X) = E[(X - \mu)^2] = \sum X(\omega)(\omega - \mu)^2 .$$

The *standard deviation* is the square root of the variance:

$$\sigma = \sqrt{Var(X)} .$$

Ordered samples of size r , with replacement

The number of ordered samples of size r with replacement from n objects

$$n \times n \times \dots = n^r$$

The number of possible outcomes if 3 dices are thrown is $6 \times 6 \times 6 = 216$.

Ordered samples of size r , without replacement

The number of ordered samples of size r without replacement from n objects is:

$$(n)_r = n \cdot (n - 1) \cdots (n - r + 1) = \frac{n!}{(n - r)!} ,$$

where $n = 1, 2, \dots, n$.

The number of 3 digit numbers that can be formed from $1, 2, \dots, 9$, if no digit can be repeated, is $9 \cdot 8 \cdot 7 = 504$.

Unordered samples of size r , without replacement

The number of unordered samples of size r without replacement from of n objects is:

$$\binom{n}{r} = \frac{n!}{r!(n-r)!}$$

How many distinct sequences can we make using 3 letter "A"s and 5 letter "B"s? (AAABBBBB, AABBBBB, etc.)

You have 8 positions total, 3 of them for As, 5 for Bs. The total number of ways is

$$\binom{8}{3} = \binom{8}{5}$$

Unordered samples of size r , with replacement

The number of ways to place r indistinguishable objects into n distinct sells is:

$$\binom{n+r-1}{r} = \binom{n+r-1}{n-1}$$

10 passengers get on an airport shuttle which stops near 5 hotels, each passengers gets off the shuttle at his/her hotel. How many possibilities exist?

$$\binom{5+10-1}{10} = \binom{5+10-1}{5-1} = \binom{14}{4}$$